

Cambridge International Examinations

Cambridge International Advanced Subsidiary and Advanced Level

PHYSICS

9702/52 March 2017

Paper 5 Planning, Analysis and Evaluation MARK SCHEME Maximum Mark: 30

Published

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| Question | Answer | Marks |
|----------|---|-------|
| 1 | Defining the problem | |
| | M is the independent variable and v is the dependent variable, or vary M and measure v | 1 |
| | keep x/compression of spring constant | 1 |
| | Methods of data collection | |
| | labelled diagram including horizontal spring in line with vehicle attached to wall/retort stand | 1 |
| | use a ruler/calliper to determine compression of spring | 1 |
| | use of stopwatch/use of light gate connected to a timer/motion sensor correctly positioned | 1 |
| | use of balance to measure mass of vehicle M | 1 |
| | Method of Analysis | |
| | plots a graph of 1 / v ² against <i>M</i> [Do not allow Ig-Ig graphs] | 1 |
| | relationship valid if a straight line produced | 1 |
| | $k = \frac{1}{gradient \times x^2} \text{ or } k = \frac{b}{y - intercept \times x^2}$ | 1 |

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| Question | Answer | Marks | |
|----------|--|-------|--|
| | Additional detail including safety considerations | Max 6 | |
| | D1 use safety screen; use goggles to avoid ball/spring hitting eye | | |
| | D2 add masses to the vehicle to change M | | |
| | D3 repeat experiment for each <i>M</i> and average <i>v</i> | | |
| | D4 use of ruler to measure an appropriate distance for the time taken in stopwatch/light gate methods | | |
| | D5 method to determine speed of vehicle, e.g. time vehicle over a measured distance <u>and</u> use speed = distance/time | | |
| | D6 method to release ball with guide or support for spring /ball | | |
| | D7 release the ball close to the vehicle | | |
| | D8 detail on determining <i>x</i> e.g. difference between compressed length and original length | | |
| | D9 method to ensure constant speed along track, e.g. friction compensate track/use of air track | | |
| | D10 (relationship valid if a straight line produced) with (<i>y</i> -)intercept = $\frac{b}{kx^2}$ | | |

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| Question | | Answer | Marks |
|----------|---|---|-------|
| 2(a) | gradient = Q/E y-intercept = 1/E | | |
| 2(b) | 4.0 or 4.00 or 4.000 | 1.5 or 1.52 | |
| | 3.0 or 3.03 or 3.030 | 1.2 or 1.16 | |
| | 2.1 or 2.13 or 2.128 | 0.870 or 0.8696 | |
| | 1.8 or 1.79 or 1.786 | 0.769 or 07692 | |
| | 1.5 or 1.47 or 1.471 | 0.671 or 0.6711 | |
| | 1.2 or 1.19 or 1.190 | 0.610 or 0.6098 | |
| | absolute uncertainties from | | |
| | Second mark for all second | | |
| 2(c)(i) | six points plotted correctly | | |
| | must be within half a small | square | |
| | error bars in 1/ <i>P</i> plotted co all error bars to be plotted | prrectly | |
| 2(c)(ii) | | ly then lower end of line should pass between (1.50, 0.70) and (1.65, 0.70) and upper end of 3.60, 1.40) and (3.80, 1.40). | |
| | worst acceptable line drawn steepest or shallowest post mark scored only if all error | sible line | |

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| Question | Answer | Marks |
|-----------|--|-------|
| 2(c)(iii) | gradient determined with a triangle that is at least half the length of the drawn line | 1 |
| | uncertainty = gradient of line of best fit – gradient of worst acceptable line or | 1 |
| | uncertainty = 1/2 (steepest worst line gradient – shallowest worst line gradient) | |
| 2(c)(iv) | <i>y</i> -intercept determined by substitution into $y = mx + c$ | 1 |
| | uncertainty = y-intercept of line of best fit – y-intercept of worst acceptable line or | 1 |
| | uncertainty = $\frac{1}{2}$ (steepest worst line <i>y</i> -intercept – shallowest worst line <i>y</i> -intercept). | |
| 2(d)(i) | <i>E</i> determined with correct unit using <i>y</i> -intercept $E = \frac{1}{y - intercept}$ | 1 |
| | <i>Q</i> determined with correct unit using gradient and given to two or three significant figures penalise power of ten errors correct substitution of numbers must be seen $Q = E \times gradient = \frac{gradient}{y - intercept}$ | 1 |
| 2(d)(ii) | percentage uncertainty in <i>Q</i> correct substitution of numbers must be seen %uncertainty <i>E</i> + %uncertainty in gradient <i>or</i> %uncertainty in <i>y</i> -intercept + %uncertainty in gradient | 1 |
| | Maximum/minimum methods | |
| | $Max Q = \max gradient \times \max E = \frac{\max gradient}{\min y - intercept}$ | |
| | $MinQ = \min gradient \times \min E = \frac{\min gradient}{\max y - intercept}$ | |